

# ABSENCE OF LOCAL MAXIMA FOR OPTIMAL CONTROL OF TWO-LEVEL QUANTUM SYSTEMS

Nikolai Il'in

Steklov Mathematical Institute of Russian Academy of Science

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Pechen A. N. and Il'in N. B. Trap-free manipulation in the  
Landau-Zener system. *Phys. Rev. A* **86**, 052117 (2012).

Pechen, Il'in. *Proceedings of the Steklov Institute of  
Mathematics*. (2014) in press.

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# 1. Our main result: no traps in the two-level system

**Theorem:** Consider two-level quantum system with controlled evolution

$$i \frac{d}{dt} U_t^f = [H_0 + f(t)V] U_t^f$$

$$H_0, V \in u(2, \mathbb{C}), f(t) \in L^1[0, T]$$

If  $\text{Tr} V = 0$  and  $T \geq \pi / (|H_0 - \frac{1}{2} \text{Tr} H_0 + V|)$ ,  $f_0 = -\text{Tr}(H_0 V) / \text{Tr}(V^2)$ , then all maxima of functionals  $J_{i \rightarrow f}(f) = |\langle \psi_f | U_T^f | \psi_i \rangle|^2$ ,  $J_O(f) = \langle \psi_f | U_T^{f\dagger} O U_T^f | \psi_i \rangle$ ,  $J_W(f) = |\text{Tr}(U_T^f W^\dagger)|^2$  (and much more general) are global that is, there are no local maxima.

## 2. Formulation of a general quantum control problem

### Formulation:

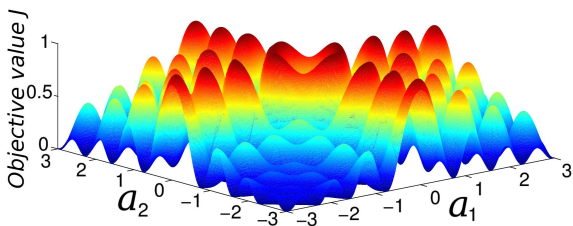
- Unitary evolution:  $i\dot{U}_t^f = [H_0 + f(t)V]U_t^f$
- Control:  $f \in L^1[0, T]$
- The goal is to maximize objective  $J(f) = F(U_T^f)$ ,  
 $F : U(n) \rightarrow \mathbb{R}$ 
  - Transition probability  $J_{i \rightarrow f}(f) = |\langle \psi_f | U_T^f | \psi_i \rangle|^2$
  - Average value  $J_O(f) = \langle \psi_f | U_T^{f\dagger} O U_T^f | \psi_i \rangle$
  - Gate generation  $J_W(f) = |\text{Tr}(U_T^f W^\dagger)|^2$

### Brief history:

- 1980-th: First works on quantum control.
- Now: Quantum control is an actively growing field. More than 1300 articles published every year according to *WebOfScience*.

### 3. Traps of $J(f)$

**Trap:** local maximum of  $J(f)$  with objective value less than the global maximum.



**Importance:** The existence of traps may prevent local algorithms from finding the global maximum. This circumstance motivates high interest to the analysis of traps.

## 4. Overview of previous results about traps

- Rabitz, Hsieh and Rosenthal (Science 2004): Conjecture of the absence of traps for quantum systems (not proved!).<sup>1</sup>
- Pechen and Tannor (PRL 2012): Prove the existence of some kind of traps for  $n > 2$ -level quantum systems with special symmetries<sup>2</sup> and hence "show mathematically that the situation is more complicated".<sup>3</sup>
- Fouquieres and Schirmer (IDAQP 2013):<sup>4</sup> Constructed examples of traps.
- Pechen and Il'in (PRA 2012) and subsequent work (PSIM 2014)<sup>5</sup>: Prove the absence of traps for the two-level system. Our work provides a first example of a trap-free quantum control system. Prior this work no examples of trap-free systems were known.

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<sup>1</sup>Rabitz, Hsieh, Rosenthal. *Science* **303**, 1998 (2004).

<sup>2</sup>Pechen, Tannor. *Phys. Rev. Lett.* **108**, 198902 (2012).

<sup>3</sup>Yeston. *Science* **332**, 514 (2011).

<sup>4</sup>Fouquieres, Schirmer. *IDAQP* **16(3)**, 1350021 (2013).

<sup>5</sup>Pechen, Il'in. *Proceedings of the Steklov Institute of Mathematics*. (2014)

## 5. Details of our main result

**Two-level system:**  $i\dot{U}_t^f = [H_0 + f(t)V]U_t^f$

**Importance:** Two-level system models a wide range of phenomena in physics, chemistry and quantum information.

**Theorem:(main result)** There are no traps for objective  $J_O(f)$ ,  $J_{i \rightarrow f}(f)$ ,  $J_W(f)$  (and for more general objectives) for the two-level system.

**Proof (Sketch):**

- $\nabla_f J(U_T^f) = 0 \Rightarrow \nabla_U J(U) \circ \nabla_f U_T^f = 0$
- $\nabla_f U_T^f = -iU_T^f U_t^{f\dagger} V U_t^f$
- $\nabla_U J(U) \Big|_{U=\nabla_f U_T^f} = 0 \Rightarrow \nabla_U J[-iU_T^f X] = 0, \forall X \in su(2)$

## 5. Details of our main result

Let  $L(X) := \nabla_U J[-iU_T^f X]$ ,  $V_t := U_t^{f\dagger} V U_t^f$ . Consider the function  $l(t) := L(V_t)$ . The equality  $L(V_t) = 0$  means  $l(t) \equiv 0$ . Therefore, in particular,  $l(t) = l'(t) = l''(t) = 0$ , that implies

- $0 = L(U_t^{f\dagger} V U_t^f)$
- $0 = L(U_t^{f\dagger} [H_0, V] U_t^f)$
- $0 = L(U_t^{f\dagger} ([H_0, [H_0, V]] + f(t)[V, [H_0, V]]) U_t^f)$

If  $f(t)$  is not equal identically to  $f_0$  then there exists  $t$  such that the matrices  $\mathbb{I}$ ,  $V$ ,  $[H_0, V]$ , and  $E_t = [H_0, [H_0, V]] + f(t)[V, [H_0, V]]$  are linearly independent.

This finishes outline of the proof.

**Remark:** Our proof assumes ideal case with unconstrained controls and without noise.



## 6. Deviations from the ideal case

In order to estimate deviations from the ideal case, we consider the system of special form

$$i \frac{d}{dt} U_t^f = [\sigma_x + f(t)\sigma_z] U_t^f$$

$\sigma_x$  and  $\sigma_z$  are Pauli matrices:  $\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ ,  $\sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

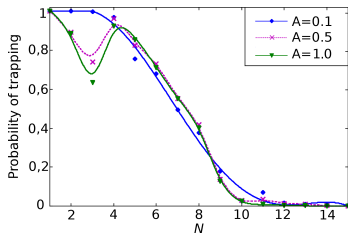
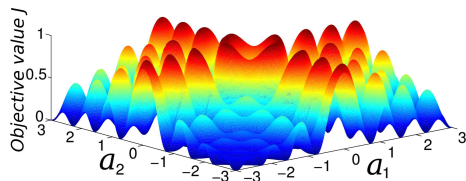
$$[\sigma_i, \sigma_j] = 2i\epsilon_{ijk}\sigma_k, \quad i, j, k = x, y, z$$

## 6. Deviations from the ideal case: constrained controls

Control field in experiments often has the following form

$$\tilde{f}(t) = \sum_{i=1}^N a_i \chi_{[t_{i+1}, t_i]}(t), \quad a_i \in [-A, A]$$

**Our result:** Constrained objective  $J(\tilde{f}) = \tilde{J}(a_1, \dots, a_n)$  has traps for small  $N$ .



Control landscape and traps for  $N = 2$       Probability of trapping for different  $N$

## 7. Deviations from the ideal case: noise in the control

Often in experiment control has noise component described by white noise with correlation function  $\langle \xi(t)\xi(t') \rangle = \sigma^2 \delta(t - t')$

- Additive:  $f \rightarrow f + \xi(t)$
- Multiplicative:  $f \rightarrow f(1 + \xi(t))$

**Our result:** Noise decreases  $\max J(f)$

$$\max \langle J(f) \rangle = \max J(f) - \sigma^2 D + o(\sigma^2)$$

Additive noise:  $D_{AWN} \leq T$  ( $T$  — control pulse duration)

Multiplicative noise:  $D_{MWN} \leq E$  ( $E = \int_0^T |f_{max}(t)|^2 dt$  — energy of the optimal control  $f_{max}$ )

## Conclusions

In this talk we presented our theorem for the absence of traps in the two-level quantum system, discuss the limitations associated with the noise and constrains in the controls and provide an overview of previous results for the analysis of traps.

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# Thank you!